

**INVERSE FUNCTIONS**

Letting D and R indicate the domain and range of the respective function,

$$D_{f^{-1}} = R_f \text{ and } R_{f^{-1}} = D_f$$

**SEQUENCE OF TRANSFORMATIONS**

Transformations to a curve  $y=f(x)$  are to be carried out in the order a, b, c then d as below  
 $d + cf(bx+a)$

**CONICS**

In general, the equation of the conic sections are represented by

$$Ax^2 + Cy^2 + Dx + Ey + F = 0, \text{ where } A \neq 0 \text{ and } C \neq 0$$

Circle	Ellipse	Parabola	Hyperbola
$A = C$	$A \neq C, AC > 0$	$A = 0 \text{ or } C = 0$	$A \neq C, AC < 0$
$(x-h)^2 + (y-k)^2 = r^2$ $r \neq 0$	$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$	$y^2 = 4ax$ $x^2 = 4ay$	$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$ $\frac{y^2}{a^2} - \frac{x^2}{b^2} = 1$
centre at (h, k) radius is r	x-intercepts at $(\pm a, 0)$ y-intercepts at $(\pm b, 0)$	foci at (a, 0) or (0, a)	Intercepts at $(\pm a, 0)$ asymptotes at $y = \pm \frac{a}{b}$ or $y = \pm \frac{b}{a}$

**DECOMPOSITION OF PARTIAL FRACTIONS**

$$\frac{px+q}{(ax+b)(cx+d)} = \frac{A}{ax+b} + \frac{B}{cx+d}$$

$$\frac{px^2+qx+r}{(ax+b)(cx+d)^2} = \frac{A}{ax+b} + \frac{B}{cx+d} + \frac{C}{(cx+d)^2}$$

$$\frac{px^2+qx+r}{(ax+b)(x^2+c^2)} = \frac{A}{ax+b} + \frac{Bx+C}{x^2+c^2}$$

**ARITHMETIC PROGRESSIONS**

$$u_n = a + (n-1)d$$

$$S_n = \frac{n}{2} [2a + (n-1)d]$$

$$S_n = \frac{n}{2} [a + u_n]$$

**SUMMATION**

$$\sum_{r=1}^n r^2 = \frac{1}{6} n(n+1)(2n+1)$$

$$\sum_{r=1}^n r^3 = \frac{1}{4} n^2(n+1)^2$$

**COMPOSITE FUNCTIONS**

For a composite function  $gf(x)$  to exist,  $R_f \subseteq D_g$

Domain of composite function  $gf(x)$ :  $D_{gf} = D_f$

Range of composite function  $gf(x)$ :  $R_{gf} \subseteq D_f$

if  $R_f = D_g$ , then  $R_{gf} = R_g$

**GEOMETRIC PROGRESSIONS**

$$u_n = ar^{n-1}$$

$$\text{If, } r \neq 1 \text{ } S_n = \frac{a(r^n - 1)}{r - 1} = \frac{a(1 - r^n)}{1 - r}$$

$$S_\infty = \frac{a}{1 - r}, \text{ if } |r| < 1$$

## DIFFERENTIATION

### BASIC RULES

$$\frac{d}{dx} x^n = nx^{n-1}$$

$$\frac{d}{dx} [f(x) \pm g(x)] = f'(x) \pm g'(x)$$

$$\frac{d}{dx} n[f(x)] = n[f'(x)]$$

### QUOTIENT RULE

$$\left( \frac{f(x)}{g(x)} \right)' = \frac{f'(x)g(x) - f(x)g'(x)}{[g(x)]^2}$$

“Low-d-high minus high-d-low over low squared”

### IMPLICIT DIFFERENTIATION

$$\frac{d}{dx} g(y) = \frac{dy}{dx} \cdot \frac{d}{dy} [g(y)] \quad \text{e.g. } \frac{d}{dx} y^2 = 2y \frac{dy}{dx}$$

Standard rules of differentiation apply.

### CHAIN RULE

$$\frac{d}{dx} f[g(x)] = f'[g(x)]g'(x)$$

e.g.

$$f(x) = x^4; \quad g(x) = x^3 + 6$$

$$\frac{d}{dx} (x^3 + 6)^4 = 4(x^3 + 6)^3 (3x^2)$$

### PRODUCT RULE

$$\frac{d}{dx} [f(x)g(x)] = f'(x)g(x) + g'(x)f(x)$$

### PARAMETRIC DIFFERENTIATION

For a parametric function  $x=f(t)$  and  $y=g(t)$

$$\frac{dy}{dx} = \frac{dy}{dt} \times \frac{dt}{dx}$$

## INTEGRATION

### BASIC RULES

$$\int (f \pm g) dx = \int f dx \pm \int g dx$$

$$\int n[f(x)] dx = n \int f(x) dx$$

$$\int x^n dx = \frac{x^{n+1}}{n+1} + c, \quad n \neq -1$$

$$\int (ax+b)^n dx = \frac{(ax+b)^{n+1}}{a(n+1)} + c, \quad n \neq -1$$

$$\int f'(x) [f(x)]^n dx = \frac{[f(x)]^{n+1}}{n+1}, \quad n \neq -1$$

### DEFINITE INTEGRALS

$$\int_a^b f(x) dx = \left[ \int f(x) dx \right]_a^b = F(b) - F(a)$$

Where  $F(x)$  is the antiderivative of  $f(x)$

$$\text{i.e., } \frac{d}{dx} F(x) = f(x)$$

### PARAMETRIC INTEGRATION

The integral of parametric function  $x=f(t)$  and  $y=g(t)$ ,

$$\int y \frac{dx}{dt} dt$$

### AREA AND VOLUME

In general, the area  $R$  between two functions  $y=f(x)$  and  $y=g(x)$  with limits  $a$  to  $b$  is given by

$$\int_a^b y dx = \int_a^b f(x) - g(x) dx$$

And the volume found when  $R$  is revolved completely around the  $x$ -axis is given by

$$\pi \int_a^b y^2 dx = \pi \int_a^b [f(x)]^2 - [g(x)]^2 dx$$

In general, the area  $Q$  between two functions  $x=f(y)$  and  $x=g(y)$  with limits  $c$  to  $d$  is given by

$$\int_c^d x dy = \int_c^d f(y) - g(y) dy$$

And the volume found when  $Q$  is revolved completely around the  $y$ -axis is given by

$$\pi \int_c^d x^2 dy = \pi \int_c^d [f(y)]^2 - [g(y)]^2 dy$$

The area bound by the parametric function  $x=f(t)$  and  $y=g(t)$  and the  $x$ -axis, with limits  $e$  to  $f$ , is given by

$$\int_p^q y \frac{dx}{dt} dt \quad \text{where } f(p)=e \text{ and } f(q)=f$$

TABLE OF DERIVATIVES

f(x)	f'(x)	f(x)	f'(x)	f(x)	f'(x)
sin x	cos x	sin <sup>-1</sup> x	$\frac{1}{\sqrt{1-x^2}}$	e <sup>x</sup>	e <sup>x</sup>
cos x	-sin x			e <sup>f(x)</sup>	f'(x)[e <sup>f(x)</sup> ]
tan x	sec <sup>2</sup> x	cos <sup>-1</sup> x	$-\frac{1}{\sqrt{1-x^2}}$	ln x	$\frac{1}{x}$
csc x	-csc x cot x			ln [f(x)]	$\frac{f'(x)}{f(x)}$
sec x	sec x tan x	tan <sup>-1</sup> x	$\frac{1}{1+x^2}$	n <sup>x</sup>	n <sup>x</sup> ln n
cot x	-csc <sup>2</sup> x			n <sup>f(x)</sup>	n <sup>f(x)</sup> f'(x)[ln n]

TABLE OF INTEGRALS

The arbitrary constant c has been omitted

f(x)	$\int f(x)dx$	f(x)	$\int f(x)dx$	f(x)	$\int f(x)dx$
$\frac{f'(x)}{f(x)}$	ln  f(x)	f'(x) cos[f(x)]	sin[f(x)]	$\frac{f'(x)}{\sqrt{a^2-[f(x)]^2}}$	$\sin^{-1} \frac{f(x)}{a} + c$
$[f'(x)]e^{f(x)}$	e <sup>f(x)</sup>	f'(x) sin[f(x)]	-cos[f(x)]	$\frac{f'(x)}{a^2+[f(x)]^2}$	$\frac{1}{a} \tan^{-1} \frac{f(x)}{a} + c$
		f'(x) sec <sup>2</sup> [f(x)]	tan[f(x)]		

POWER SERIES

MACLAURIN'S SERIES

$$f(x) = f(0) + f'(0)x + \frac{f''(0)x^2}{2!} + \frac{f^{(3)}(0)x^3}{3!} + \dots + \frac{f^{(n)}(0)x^n}{n!} + \dots$$

SMALL ANGLE APPROXIMATION

$$\begin{aligned} \sin \theta &\approx \theta \\ \tan \theta &\approx \theta \\ \cos \theta &\approx 1 - \frac{\theta^2}{2} \end{aligned}$$

COMPLEX NUMBERS

FORMS OF A COMPLEX NUMBER Z

$$\begin{aligned} z &= x + iy \\ &= r(\cos\theta + i\sin\theta) \\ &= r e^{i\theta} \end{aligned}$$

Where r=|z| and  $\theta=\arg(z)$

PROPERTIES OF CONJUGATE PAIRS

$$\begin{aligned} (z^*)^* &= z \\ z + z^* &= 2\text{Re}(z) \\ z - z^* &= 2i \text{Im}(z) \\ zz^* &= x^2 + y^2 \end{aligned}$$

MULTIPLICATION OF COMPLEX NUMBERS

$$\begin{aligned} |z_1 z_2| &= |z_1| |z_2| = r_1 r_2 \\ \arg(z_1 z_2) &= \arg(z_1) + \arg(z_2) = \theta_1 + \theta_2 \end{aligned}$$

DIVISION OF COMPLEX NUMBERS

$$\begin{aligned} \left| \frac{z_1}{z_2} \right| &= \frac{|z_1|}{|z_2|} = \frac{r_1}{r_2} \\ \arg\left(\frac{z_1}{z_2}\right) &= \arg(z_1) - \arg(z_2) = \theta_1 - \theta_2 \end{aligned}$$

DE MOIVRE'S THEOREM

$$\begin{aligned} \text{if } z &= r(\cos\theta + i\sin\theta), \\ \text{then } z^n &= r^n(\cos\theta + i\sin\theta)^n \\ &= r^n(\cos(n\theta) + i\sin(n\theta)) \end{aligned}$$

## VECTORS

### EQUATIONS OF A LINE

The vector equation of a line  $l$  which passes through point A with position vector  $\mathbf{a}$  and is parallel to a vector  $\mathbf{b}$  is given by  $l: \mathbf{r} = \mathbf{a} + \lambda\mathbf{b}$

The line with Cartesian equation  $\frac{x-a_1}{b_1} = \frac{y-a_2}{b_2} = \frac{z-a_3}{b_3}$  has a vector equation  $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} + \lambda \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$

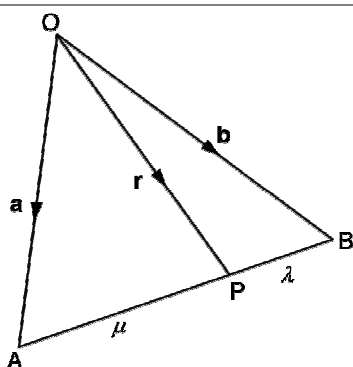
### EQUATIONS OF A PLANE

The vector equation of a plane  $\pi$  which passes through point A with position vector  $\mathbf{a}$  and is parallel to two non parallel vectors  $\mathbf{b}$  and  $\mathbf{c}$  is given by  $\pi: \mathbf{r} = \mathbf{a} + \lambda\mathbf{b} + \mu\mathbf{c}$

The equation of the plane in scalar product form is given by  $\pi: \mathbf{r} \cdot \mathbf{n} = p$ , where  $\mathbf{r}$  is a position vector of any point on the plane  $\pi$  and  $\mathbf{n}$  is the normal vector

The plane with Cartesian equation  $\pi: n_1x + n_2y + n_3z = p$  has the equation  $\mathbf{r} \cdot \begin{pmatrix} n_1 \\ n_2 \\ n_3 \end{pmatrix} = p$

### RATIO THEOREM



For any point P that divides the line AB in the ratio  $\lambda:\mu$ , the vector  $\mathbf{r}$  is given by  $\frac{\lambda\mathbf{a} + \mu\mathbf{b}}{\lambda + \mu}$

### LENGTH OF PROJECTION

The length of projection of  $\mathbf{a}$  onto  $\mathbf{b}$  is given by  $|\mathbf{a} \cdot \hat{\mathbf{b}}|$

### FOOT OF PERPENDICULAR

#### From a point to a line

The foot, F, of the perpendicular of a point C with position vector  $\mathbf{c}$  to a line with equation  $\mathbf{r} = \mathbf{a} + \lambda\mathbf{b}$  is given by the equations relating

- 1)  $\mathbf{OF} = \mathbf{a} + \lambda\mathbf{b}$
- 2)  $\mathbf{OF} \cdot \mathbf{b} = 0$

#### From a point to a plane

The foot, Q, of the perpendicular of a point P with position vector  $\mathbf{p}$  to a plane with normal  $\mathbf{n}$  is given by the equations relating

- 1)  $\mathbf{OQ} = \mathbf{p} + \lambda\mathbf{n}$
- 2)  $\mathbf{OQ} \cdot \mathbf{n} = p$

### PERPENDICULAR DISTANCE

In addition, the perpendicular distance from  $\mathbf{a}$  to  $\mathbf{b}$  is given by  $|\mathbf{a} \times \hat{\mathbf{b}}|$

### SCALAR PRODUCT

$$\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos \theta$$

where  $\theta$  is the angle between the two vectors

Algebraically,  $\begin{pmatrix} x_1 \\ y_2 \\ z_3 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ y_2 \\ z_3 \end{pmatrix} = x_1x_2 + y_1y_2 + z_1z_2$

Important results to note are:

$$\mathbf{a} \cdot \mathbf{a} = |\mathbf{a}|^2$$

$\mathbf{a} \cdot \mathbf{a} = 0$  when the vectors are perpendicular

### VECTOR PRODUCT

$$\mathbf{a} \times \mathbf{b} = (|\mathbf{a}| |\mathbf{b}| \sin \theta) \hat{\mathbf{n}}$$

where  $\theta$  is the angle between the two vectors

Algebraically,  $\begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} \times \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} = \begin{pmatrix} y_1z_2 - z_1y_2 \\ -(x_1z_2 - z_1x_2) \\ x_1y_2 - y_1x_2 \end{pmatrix}$